COMPARATIVE ANALYSIS OF FRAMEWORKS FOR THE PERFORMANCE EVALUATION OF MULTI-TIER CLOUD APPLICATIONS

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 - RTC Fundamentals
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Objective

- We address the performance evaluation of multi-tier clouds applications
- We compare a Real-Time Calculus-based framework with two classical analytical approaches such as queuing theoretic approaches and control theoretic approaches
- We focus on the capabilities of these alternatives for estimating the key Quality of Service parameter the application response-time

Motivation



Imaginary example of a client session on a basic multi-tier application architecture (note that in virtualized cloud platforms, each software server, i.e., Apache, Tomcat, and MySQL, is run inside of a virtual machine).

Motivation



Focus of attention: Predicting Web-application response-time in cloud computing platform, e.g., does maximum request-to-response latency of a client data access request will not exceed application deadline (with 95% confidence interval)?

Analytical Frameworks Review

- Queuing models
- Control theory models
- Modular Performance Analysis with RTC

Modular Performance Analysis with RTC

- Deterministic analysis (Thiele et. al)
 - RTC belongs to the class of so-called deterministic queuing theories
 - RTC is deterministic in the sense that hard upper and lower bounds of the performance metrics (such as latency) can be always found
- Stochastic analysis (Garay, 2013)
 - Soft real-time guarantees, i.e., guarantees on delays and backlogs that are valid up to a certain level of confidence

G. R. Garay, J. Ortega, A. F. Díaz, L. Corrales, and V. Alarcón-Aquino, "System performance evaluation by combining RTC and VHDL simulation: A case study on NICs," *Journal of Systems Architecture,* vol. 59, pp. 1277-1298, 2013.

RTC Fundamentals

- Arrival and Service Functions
- Arrival and Service Curves
- Worst-case analysis:
 - Maximum Backlog
 - Maximum delay

Arrival and Service Functions

- An event stream can be described by an arrival function R, where R(t) denotes the number of events that have arrived in the interval [0, t)
- A computing or communication resource can be described by a service function C, where C(t) denotes the number of events that could have been served in the interval [0, t)

Arrival and Service Curves

The **upper and lower arrival curves**, $\alpha^u(\Delta)$, $\alpha^l(\Delta) \in \mathbb{R}^{\geq 0}$ of an arrival function R(t) satisfy the following inequality:

$$\alpha^{l}(t-s) \leq R(t) - R(s) \leq \alpha^{u}(t-s), \forall s, t: 0 \leq s \leq t$$

Arrival and Service Curves

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Modular Performance Analysis with RTC



Both, α_f^u arrival curve and β_r^l service curve are **bounding-functions** and can be defined using a piecewise linear approximation



Deriving the α_f^u and β_r^l bounding-functions of the processing resource r.



(b)

RTC model parameters and our metric of interest (D_{max}) .



Modeling the resource r and obtaining its maximum requestresponse delay time (D_{max}) by using RTC.

 $delay \leq sup_{t\geq 0} \big\{ \inf \big\{ \tau \geq 0 : \ \alpha_f^u(t) \leq \ \beta_r^l(t + \tau) \big\} \big\}$

Modular Performance Analysis with RTC



RTC model calibration



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RTC model calibration

Deriving the parameters for constructing the $\beta_{r_i}^l$ lower service curve of a concrete system component with non-deterministic behavior (e.g., a web, application or database server) from simulations or real traces may give the case where the following assumption holds

$$\exists i, \Delta: \beta_{r_i}^l(\Delta) < \beta_{\{r_i, reality\}}^l(\Delta)$$

where $i \in (1, 2, 3, ...)$, $\beta_{r_i}^l$ is a resultant lower service curve derived from a set of lower service curves and , $\beta_{\{r_i, reality\}}^l(\Delta)$ is an unknown lower bounding-curve of the SUT for the stochastic component being considered.

For this reason, in (Garay, 2013), statistical methods are used in order to demonstrate that the values of the *L* and *R* parameters of $\beta_{r_i}^l$ have an adequate level of predictability, and, hence, results are valid up to certain level of confidence.

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Comparison of analytical approaches

Modeling capabilities	MPA-RTC	Queuing Theory	Control Theory
Multi-tier cloud Web application	Yes	Yes	Yes
Hard/Soft response time guarantees	Both	No	Soft guarantees
Workload models	Real and/or synthetic	Synthetic	Real or synthetic
Task processing models	Real and/or synthetic	Synthetic	Real or synthetic
VM provisioning	Yes	Yes	Yes
VMs performance interference effect	Yes	Yes	Yes
Autonomic resource management	Yes	Yes	Yes
Server consolidation	Yes	Yes	Yes
Horizontal/Vertical scaling	Both	Both	Both

In our paper, references to analytical studies based on queuing theory (QT) and control theory (CT) are given and a discussion on the modeling capabilities of each approach is presented

Workload models

- Real workload traces
- Naive synthetic workload models (e.g., probability distributions)
- Realistic synthetic workload models
- Combinations of the previous alternatives

Modeling provisioning response delay



Non-processing time interval

VMs performance interference effect



RTC-based autonomic resource management



VMs deployment scenarios



Horizontal scaling



Conclusion

- We discuss different approaches for modeling cloudbased systems
- We conclude that RTC is suitable framework for estimating statistical response time guarantees
- We consider that contemporary issues in cloud computing research could be analyzed by using MPA-RTC

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